

IS27DV256

32,768 x 8 DUAL VOLTAGE CMOS EPROM

ADVANCE INFORMATION
FEBRUARY 1998

FEATURES

- Dual voltage range operation:
3.0 to 3.6V or 5V \pm 10%
- Fast access time: 90 ns
- JEDEC-approved pinout
- Low power consumption (3.0 to 3.6V)
 - 30 μ A (max) standby current
 - 29 mW (max) active current at 5 MHz
- High-speed write programming
 - Typically less than eight seconds
- Industrial and commercial temperature ranges available
- Standard 28-pin DIP and TSOP, and 32-pin PLCC packages

DESCRIPTION

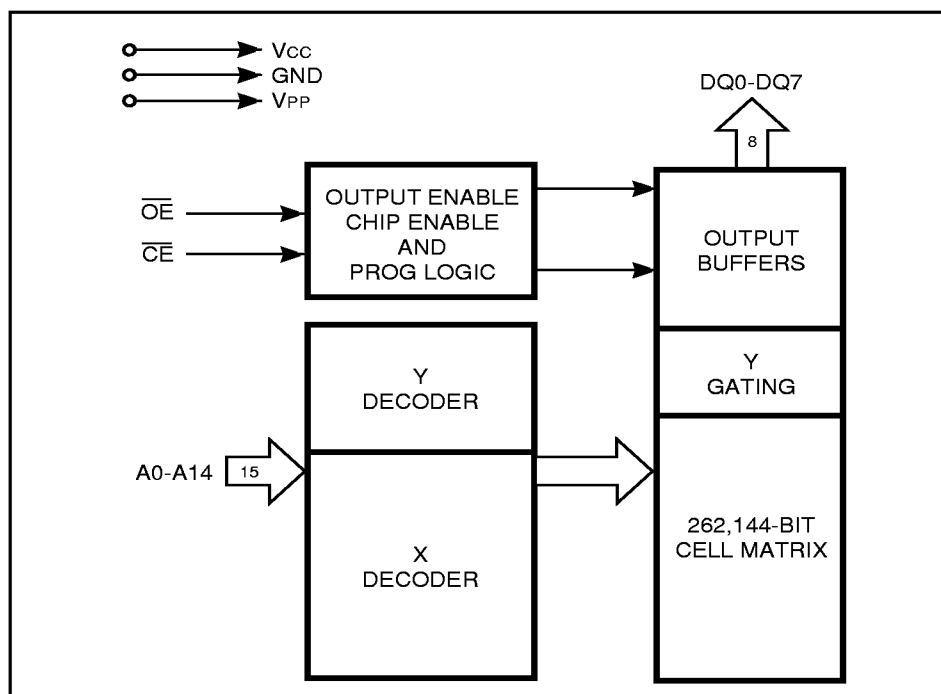
The *ISSI* IS27DV256 is a dual voltage, low power, high-speed 256K-bit CMOS (32K-word by 8-bit) CMOS Programmable Read-Only Memory. It utilizes the standard JEDEC pinout making it functionally compatible with the IS27C256 EPROM.

The superior access time combined with low power consumption is the result of innovative design and process technology. If the device is constantly accessed at 5 MHz, then the maximum power consumption is 22 mW for a 3.0V supply.

The IS27DV256 uses *ISSI*'s write programming algorithm which allows the entire chip to be programmed in typically less than thirty seconds.

This product is available in One-Time Programmable (OTP) PDIP, PLCC, and TSOP packages over commercial and industrial temperature ranges.

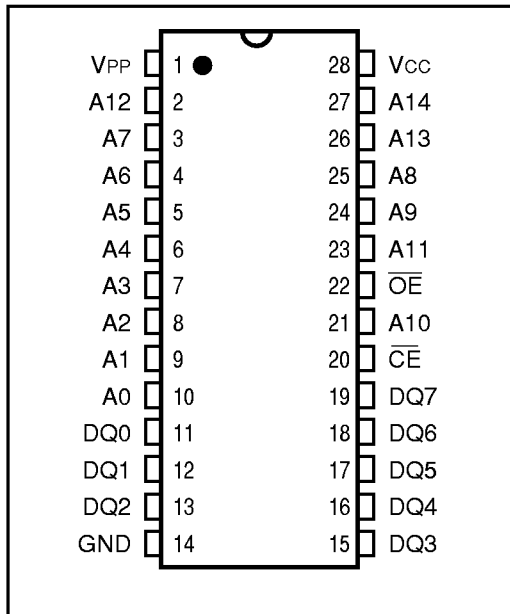
FUNCTIONAL BLOCK DIAGRAM



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PIN CONFIGURATIONS

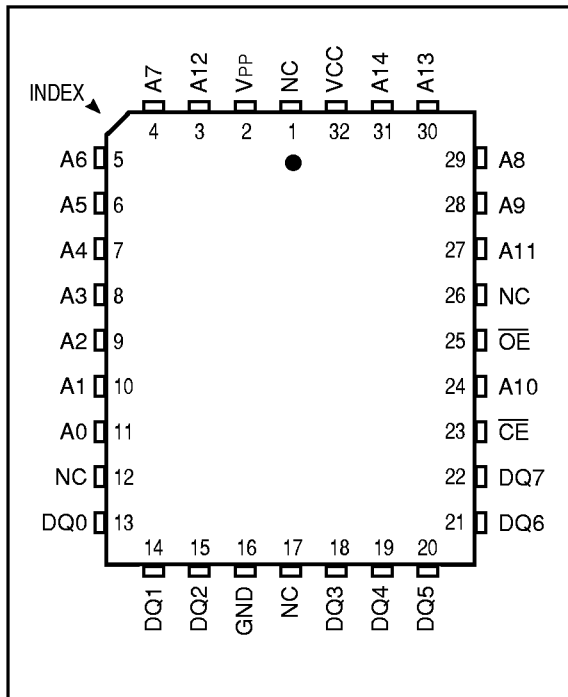
28-Pin DIP



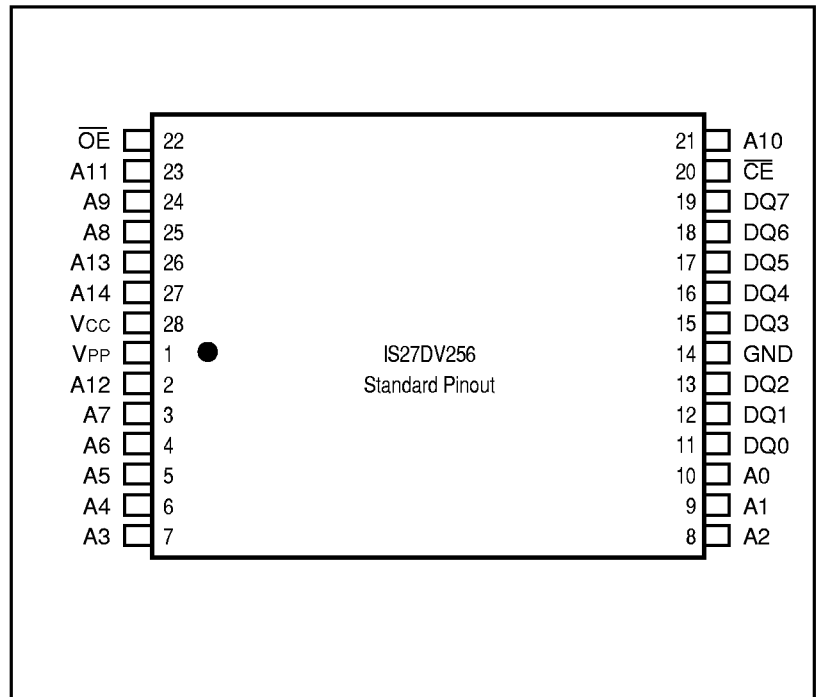
PIN DESCRIPTIONS

A0-A14	Address Inputs
\overline{CE}	Chip Enable Input
DQ0-DQ7	Data Inputs/Outputs
\overline{OE}	Output Enable Input/ Program Voltage Input
V _{CC}	Power Supply Voltage
V _{PP}	Program Supply Voltage
GND	Ground
NC	No Internal Connection

32-Pin PLCC



28-Pin TSOP



FUNCTIONAL DESCRIPTION

Programming the IS27DV256

Upon delivery the IS27DV256 has 262,144 bits in the "ONE", or HIGH state. "ZEROS" are loaded into the IS27DV256 through the procedure of programming.

The programming mode is entered when $12.5 \pm 0.25V$ is applied to the V_{PP} pin, $V_{CC} = 6V$, \overline{CE} is at V_{IL} and \overline{OE} is at V_{IH} . For programming, the data to be programmed is applied eight bits in parallel to the data output pins.

The write programming algorithm reduces programming time by using 100 μs programming pulses followed by a byte verification to determine whether the byte has been successfully programmed. If the data does not verify, an additional pulse is applied for a maximum of 25 pulses. This process is repeated while sequencing through each address of the EPROM.

The write programming algorithm programs and verifies at $V_{CC} = 6V$ and $V_{PP} = 12.5V$. After the final address is completed, all byte are compared to the original data with $V_{CC} = 5.25V$.

Program Inhibit

Programming of multiple IS27DV256s in parallel with different data is also easily accomplished. Except for \overline{CE} , all like inputs of the parallel IS27DV256 may be common. A TTL low-level program pulse applied to an IS27DV256 \overline{CE} input with $V_{PP} = 12.5 \pm 0.25V$ will program that IS27DV256. A high-level \overline{CE} input inhibits the other IS27DV256 from being programmed.

Program Verify

A verify should be performed on the programmed bits to determine that they were correctly programmed. The verify should be performed with \overline{CE} at V_{IH} and \overline{OE} at V_{IL} WITH $V_{PP} = 12.5V \pm 0.25V$.

Auto Select Mode

The auto select mode allows the reading out of a binary code from an EPROM that will identify its manufacturer and type. This mode is intended for use by programming equipment for the purpose of automatically matching the device to be programmed with its corresponding programming algorithm. This mode is functional in the $25^{\circ}C \pm 5^{\circ}C$ ambient temperature range that is required when programming the IS27DV256.

To activate this mode, the programming equipment must force $12.0 \pm 0.5V$ on address line A9 of the IS27DV256. Two identifier bytes may then be sequenced from the device outputs by toggling address line A0 from V_{IL} to V_{IH} . All other address lines must be held at V_{IL} during auto select mode.

Byte 0 ($A0 = V_{IL}$) represents the manufacturer code, and byte 1 ($A0 = V_{IH}$), the device identifier code. For the IS27DV256, these two identifier bytes are given in the Mode Select table. All identifiers manufacturer and device codes will possess odd parity, with the MSB (DQ7) defined as the parity bit.

Read Mode

The IS27DV256 has two control functions, both of which must be logically satisfied in order to obtain data at the outputs. Chip Enable (\overline{CE}) is the power control and should be used for device selection. Assuming that addresses are stable, address access time (t_{ACC}) is equal to the delay from \overline{CE} to output (t_{CE}). Output Enable (\overline{OE}) is the output control and should be used to get data to the output pins, independent of device selection. Data is available at the outputs t_{OE} after the falling edge of \overline{OE} assuming that \overline{CE} has been LOW and addresses have been stable for at least $t_{ACC} - t_{OE}$.

Standby Mode

The IS27DV256 has a standby mode which reduces the maximum V_{CC} active current. It is placed in standby mode when \overline{CE} is at V_{IH} . The amount of current drawn in standby mode depends on the frequency and the number of address pins switching. The IS27DV256 is specified with 50% of the address lines toggling at 5 MHz. A reduction of the frequency or quantity of address lines toggling will significantly reduce the actual standby current.

Output OR-Tieing

To accommodate multiple memory connections, a two-line control function is provided to allow for:

1. Low memory power dissipation, and
2. Assurance that output bus contention will not occur.

It is recommended that \overline{CE} be decoded and used as the primary device-selecting function, while \overline{OE} be made a common connection to all devices in the array and connected to the READ line from the system control bus. This assures that all deselected memory devices are in their low-power standby mode and that the output pins are only active when data is desired from a particular memory device.

System Applications

During the switch between active and standby conditions, transient current peaks are produced on the rising and falling edges of Chip Enable. The magnitude of these transient current peaks is dependent on the output capacitance loading of the device at a minimum, a 0.1 μF ceramic capacitor (high-frequency, low inherent inductance) should be used on each device between V_{CC} and GND to minimize transient effects. In addition, to overcome the voltage drop caused by the inductive effects of the printed circuit board traces on EPROM arrays, a 4.7 μF bulk electrolytic capacitor should be used between V_{CC} and GND for each eight devices. The location of the capacitor should be close to where the power supply is connected to the array.

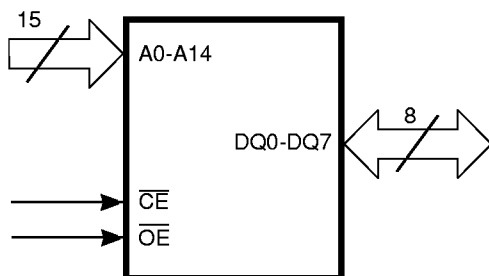
TRUTH TABLE^(1,2,4)

Mode	\overline{CE}	\overline{OE}	V_{PP}	A0	A9	Outputs
Read	V_{IL}	V_{IL}	V_{CC}	X	X	D _{OUT}
Output Disable	V_{IL}	V_{IH}	V_{CC}	X	X	Hi-Z
Standby	V_{IH}	X	V_{CC}	X	X	Hi-Z
Program	V_{IL}	V_{IH}	V_{PP}	X	X	D _{IN}
Program Verify	V_{IH}	V_{IL}	V_{PP}	X	X	D _{OUT}
Program Inhibit	V_{IH}	V_{IH}	V_{PP}	X	X	Hi-Z
Auto Select ^(3,5)	Manufacturer Code	V_{IL}	V_{CC}	V_{IL}	V_{H}	D5H
	Device Code	V_{IL}	V_{CC}	V_{IH}	V_{H}	10H

Notes:

1. $V_{H} = 12.0V \pm 0.5V$.
2. X = Either V_{IH} or V_{IL} .
3. A1-A8 = A10-A14 = V_{IL} .
4. See DC Programming Characteristics for V_{PP} voltage during programming.
5. The IS27DV256 can use the same write algorithm during program as other IS27DV256 devices.
6. Read, output disable, and standby modes require $2.7V \leq V_{CC} \leq 3.6V$, $4.5V \leq V_{CC} \leq 5.5V$.

LOGIC SYMBOL



ABSOLUTE MAXIMUM RATINGS⁽¹⁾

Symbol	Parameter	Value	Unit
V _{TERM}	Terminal Voltage with Respect to GND		
	All pins except A9 and V _{PP}	-0.6 to V _{CC} + 0.5 ⁽²⁾	V
	V _{PP}	V _{CC} - 0.3 to 13.5 ^(2,3)	V
	A9	-0.6 to 13.5 ^(2,3)	V
	V _{CC}	-0.6 to 7.0 ⁽²⁾	V
T _A	Ambient Temperature with Power Applied	-65 to +125	°C
T _{STG}	Storage Temperature (OTP)	-65 to +125	°C
T _{STG}	Storage Temperature (All others)	-65 to +150	°C

Notes:

1. Stress greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.
2. Minimum DC input voltage is -0.5V. During transitions, inputs may undershoot to -2.0V for periods less than 10 ns. Maximum DC voltage on output pins is V_{CC} + 0.5V which may overshoot to V_{CC} + 2.0V for periods less than 10 ns.
3. Maximum DC voltage on A9 or V_{PP} may overshoot to +13.5V for periods less than 10 ns.

OPERATING RANGE

Range	Ambient Temperature	V _{CC}	V _{CC}
Commercial	0°C to +70°C	5V ± 10%	3.0V to 3.6V
Industrial ⁽¹⁾	-40°C to +85°C	5V ± 10%	3.0V to 3.6V

Note:

1. Operating ranges define those limits between which the functionality of the device is guaranteed.

DC ELECTRICAL CHARACTERISTICS^(1,2,3) (Over Operating Range)

Symbol	Parameter	Test Conditions	Min.	Max.	Unit
V _{OH}	Output HIGH Voltage	V _{CC} = Min., I _{OH} = -400 μA	2.4	—	V
V _{OL}	Output LOW Voltage	V _{CC} = Min., I _{OL} = 2.1 mA	—	0.4	V
V _{IH}	Input HIGH Voltage ⁽⁴⁾		2.0	V _{CC} + 0.5	V
V _{IL}	Input LOW Voltage ⁽⁴⁾		-0.3	0.8	V
I _{LI}	Input Load Current	V _{IN} = 0V to +V _{CC}	—	5	μA
I _{LO}	Output Leakage Current	V _{OUT} = 0V to +V _{CC}	—	5	μA

Notes:

1. V_{CC} must be applied simultaneously or before V_{PP} and removed simultaneously or after V_{PP}. Never try to force V_{PP} LOW to 1V below V_{CC}. Manufacturer suggests to tie V_{PP} and V_{CC} together during the READ operation.
2. **Caution:** the IS27DV256 must not be removed from (or inserted into) a socket when V_{CC} or V_{PP} is applied.
3. Minimum DC input voltage is -0.5V. During transitions, the inputs may undershoot to -2.0V for periods less than 10 ns. Maximum DC voltage on output pins is V_{CC} + 0.5V which may overshoot to V_{CC} + 2.0V for periods less than 10 ns.
4. Tested under static DC conditions.

POWER SUPPLY CHARACTERISTICS^(1,2,4) ($V_{CC} = 5V \pm 10\%$)

Symbol	Parameter	Test Conditions	Min.	Max.	Unit
I _{CC1}	V _{CC} Operating Supply Current ⁽³⁾	V _{CC} = Max., $\overline{CE} = V_{IL}$ I _{OUT} = 0 mA, f = 5 MHz (Open outputs)	Commercial — Industrial —	15 20	mA
I _{PP1}	V _{PP} Current During Read ⁽⁴⁾	V _{CC} = Max., $\overline{CE} = \overline{OE} = V_{IL}$ V _{PP} = V _{CC}	—	100	μA
I _{CCSB0}	V _{CC} CMOS Standby Current	$\overline{CE} \geq V_{CC} - 0.3V$ All pins $\geq V_{CC} - 0.3V$ or $\leq 0.3V$	—	50	μA
I _{CCSB1}	V _{CC} TTL Standby Current	$\overline{CE} \geq V_{IH}$ All pins = V _{IH} or V _{IL} (TTL Level)	—	1	mA

POWER SUPPLY CHARACTERISTICS^(1,2,4) ($V_{CC} = 3.0V$ to $3.6V$)

Symbol	Parameter	Test Conditions	Min.	Max.	Unit
I _{CC1}	V _{CC} Operating Supply Current ⁽³⁾	V _{CC} = Max., $\overline{CE} = V_{IL}$ I _{OUT} = 0 mA, f = 5 MHz (Open outputs)	Commercial — Industrial —	8 10	mA
I _{PP1}	V _{PP} Current During Read ⁽⁴⁾	V _{CC} = Max., $\overline{CE} = \overline{OE} = V_{IL}$ V _{PP} = V _{CC}	—	100	μA
I _{CCSB0}	V _{CC} CMOS Standby Current	$\overline{CE} \geq V_{CC} - 0.3V$ All pins $\geq V_{CC} - 0.3V$ or $\leq 0.3V$	—	20	μA
I _{CCSB1}	V _{CC} TTL Standby Current	$\overline{CE} \geq V_{IH}$ All pins = V _{IH} or V _{IL} (TTL Level)	—	1	mA

Notes:

- V_{CC} must be applied simultaneously or before V_{PP} and removed simultaneously or after V_{PP}. Never try to force V_{PP} LOW to 1V below V_{CC}. Manufacturer suggests to tie V_{PP} and V_{CC} together during the READ operation.
- Caution:** the IS27DV256 must not be removed from (or inserted into) a socket when V_{CC} or V_{PP} is applied.
- I_{CC1} is tested with $\overline{OE}/V_{PP} = V_{IH}$ to simulate open outputs.
- Minimum DC input voltage is -0.5V. During transitions, the inputs may undershoot to -2.0V for periods less than 10 ns. Maximum DC voltage on output pins is V_{CC} + 0.5V which may overshoot to V_{CC} + 2.0V for periods less than 10 ns.

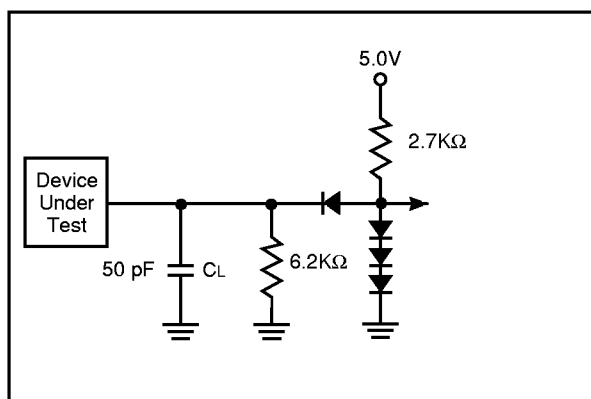
CAPACITANCE^(1,2,3)

Symbol	Parameter	Conditions	DIP		PLCC/TSOP		Unit
			Typ.	Max.	Typ.	Max.	
C _{IN}	Input Capacitance	V _{IN} = 0V	6	10	6	9	pF
C _{OUT}	Output Capacitance	V _{OUT} = 0V	8	12	6	9	pF

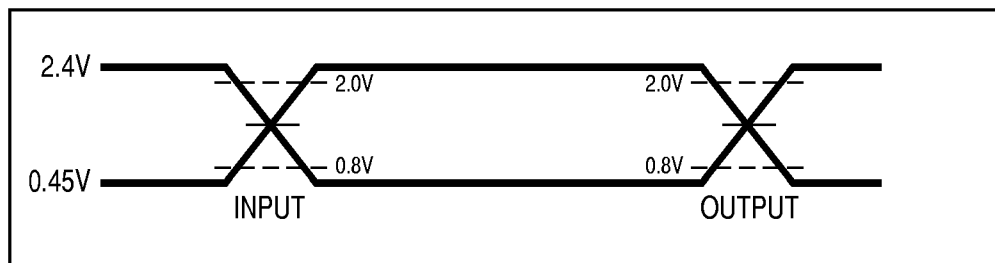
Notes:

1. Typical values are for nominal supply voltage.
2. This parameter is only sampled, but not 100% tested.
3. Test conditions: T_A = 25°C, f = 1 MHz.

SWITCHING TEST CIRCUIT



SWITCHING TEST WAVEFORM

**Notes:**

AC Testing:

1. Inputs are driven at 2.4V for a logic "1" and .45V for a logic "0".
2. Input pulse rise and fall times are < 20ns.

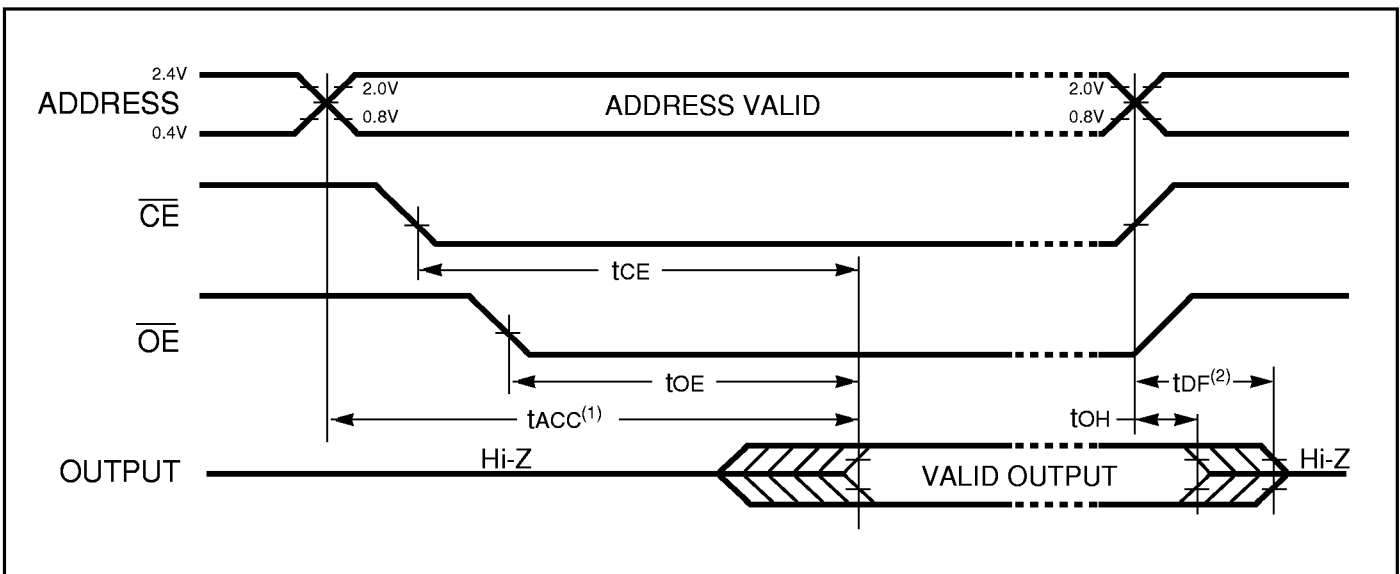
SWITCHING CHARACTERISTICS^(1,2,3,4) (Over Operating Range)

JEDEC Symbol	Std. Symbol	Parameter	Test Conditions	-90		-12		-15		Unit
				Min.	Max.	Min.	Max.	Min.	Max.	
t _{AVQA}	t _{ACC}	Address to Output Delay	$\overline{CE} = \overline{OE} = V_{IL}$ C _L = C _{L1}	—	90	—	120	—	150	ns
t _{ELQV}	t _{CE}	Chip Enable to Output Delay	$\overline{OE} = V_{IL}$ C _L = C _{L1}	—	90	—	120	—	150	ns
t _{GLQV}	t _{OE}	Output Enable to Output Delay	$\overline{CE} = V_{IL}$ C _L = C _{L1}	—	45	—	50	—	65	ns
t _{EHOZ} , t _{GHQZ}	t _{DF} ⁽²⁾	Chip Enable HIGH or Output Enable HIGH, whichever comes first, to Output Float	C _L = C _{L2}	0	30	0	35	0	35	ns
t _{AVOX}	t _{OH}	Output Hold from Address, \overline{CE} or \overline{OE} whichever occurred first		0	—	0	—	0	—	ns

Notes:

- V_{CC} must be applied simultaneously or before V_{PP} and removed simultaneously or after V_{PP}.
- This parameter is only sampled, not 100% tested.
- Caution:** The IS27DV256 must not be removed from (or inserted into) a socket or board when V_{PP} or V_{CC} applied.
- Output Load: 1 TTL gate and C_L = 50 pF
Input Rise and Fall times: 20 ns.
Input Pulse Levels: 0.45 to 2.4V.
Timing Measurement Reference Level: 0.8V to 2.0V for inputs and outputs.

SWITCHING WAVEFORMS

**Notes:**

- \overline{OE} may be delayed up to t_{ACC} - t_{OE} after the falling edge of \overline{CE} without impact on t_{ACC}.
- t_{DF} is specified from \overline{OE} or \overline{CE} , whichever occurs first.

DC PROGRAMMING CHARACTERISTICS^(1,2,3) ($T_A = +25^\circ\text{C} \pm 5^\circ\text{C}$)

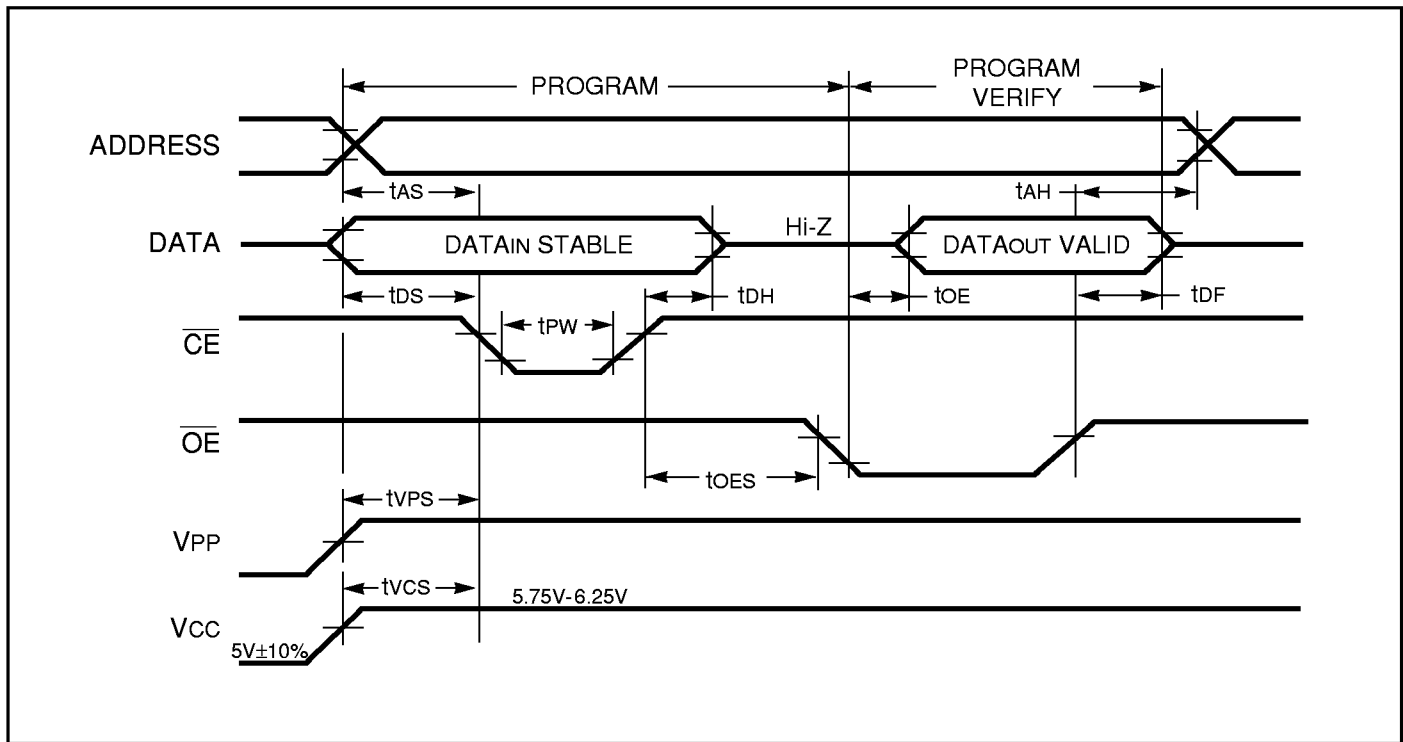
Symbol	Parameter	Test Conditions	Min.	Max.	Unit
V _{OH}	Output HIGH Voltage During Verify	I _{OH} = -400 μ A	2.4	—	V
V _{OL}	Output LOW Voltage During Verify	I _{OL} = 2.1 mA	—	0.4	V
V _{IH}	Input HIGH Voltage		2.0	V _{CC} + 0.5	V
V _{IL}	Input LOW Voltage (All Inputs)		-0.3	0.8	V
V _H	A9 Auto Select Voltage		11.5	12.5	V
I _{LI}	Input Current (All Inputs)	V _{IN} = V _{IL} or V _{IH}	—	10.0	μ A
I _{CC}	V _{CC} Supply Current (Program & Verify)		—	50	mA
I _{PP}	V _{PP} Supply Current	$\overline{\text{CE}} = \text{V}_{\text{IL}}, \overline{\text{OE}} = \text{V}_{\text{IH}}$	—	30	mA
V _{CC}	Supply Voltage		5.75	6.25	V
V _{PP}	Programming Voltage		12.25	12.75	V

SWITCH PROGRAMMING CHARACTERISTICS^(1,2,3) ($T_A = +25^\circ\text{C} \pm 5^\circ\text{C}$)

JEDEC Symbol	Std. Symbol	Parameter	Min.	Max.	Unit
t _{AVEL}	t _{AS}	Address Setup Time	2	—	μ s
t _{EHGL}	t _{OEH}	$\overline{\text{OE}}$ Hold Time	2	—	μ s
t _{DVEL}	t _{DS}	Data Setup Time	2	—	μ s
t _{GHAX}	t _{AH}	Address Hold Time	0	—	μ s
t _{EHDX}	t _{DH}	Data Hold Time	2	—	μ s
t _{EHQZ}	t _{DFP}	$\overline{\text{CE}}$ HIGH to Output Float Delay	0	130	ns
t _{VPS}	t _{VPS}	V _{PP} Setup Time	2	—	μ s
t _{ELEH1}	t _{PW}	$\overline{\text{CE}}$ Program Pulse Width	95	105	μ s
t _{VCS}	t _{VCS}	V _{CC} Setup Time	2	—	μ s
t _{GLEL}	t _{VR}	$\overline{\text{OE}}$ Recovery Time	2	—	μ s
t _{ELQV}	t _{DV}	Data Valid from $\overline{\text{CE}}$	—	150	ns

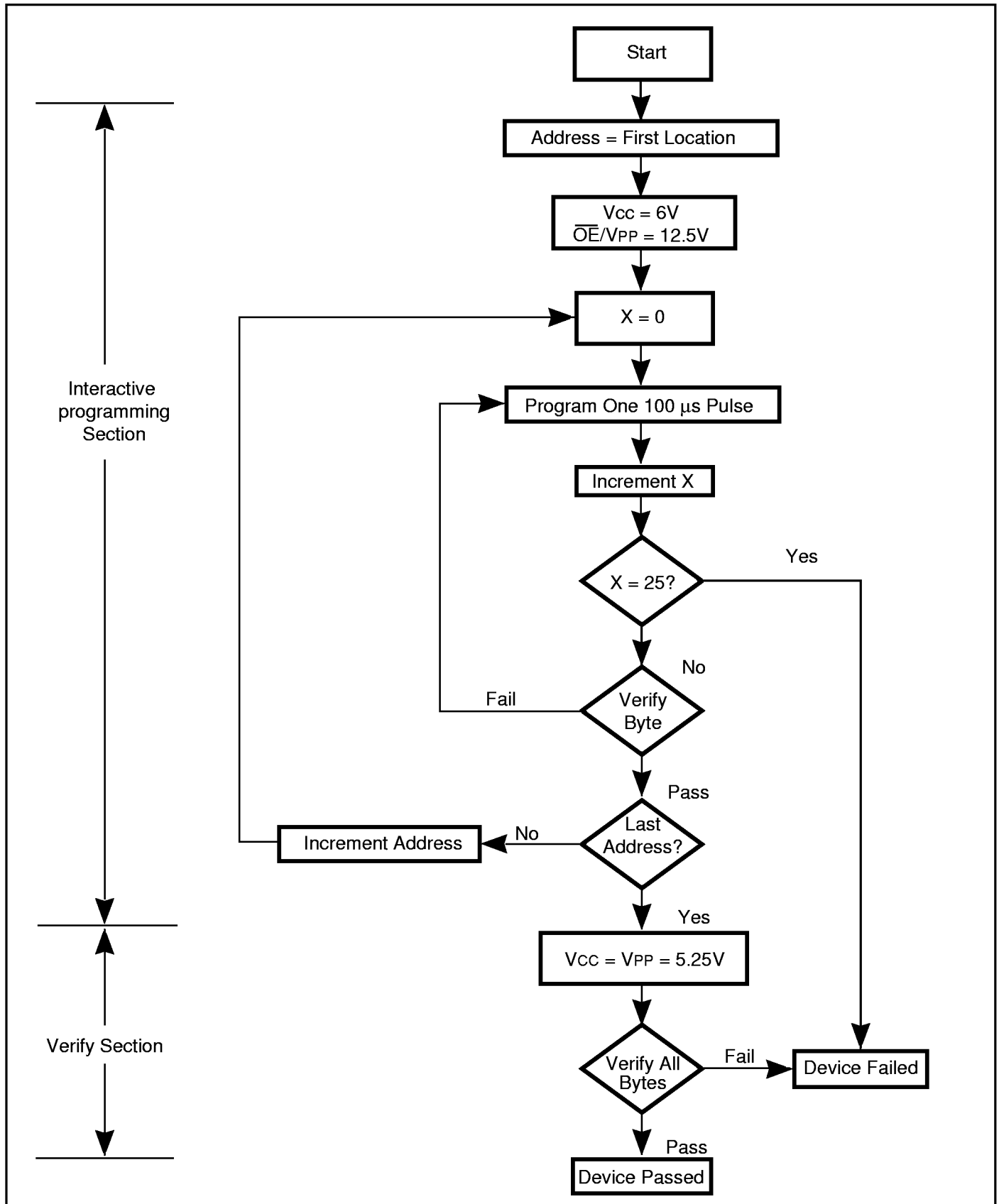
Notes:

- V_{CC} must be applied simultaneously or before V_{PP} and removed simultaneously or after V_{PP}.
- When programming IS27DV256, a 0.1 μ F capacitor is required across V_{PP} and ground to suppress spurious voltage transients which may damage the device.
- Programming characteristics are sampled but not 100% tested at worst-case conditions.

PROGRAMMING ALGORITHM WAVEFORM^(1,2)**Notes:**

1. The timing reference level is 0.8V to 2V for inputs and outputs.
2. t_{OE} and t_{DFP} are characteristics of the device but must be accommodated by the programmer.

PROGRAMMING FLOW CHART



ORDERING INFORMATION**Commercial Range: 0°C to +70°C**

Speed (ns)	Order Part Number	Package
90	IS27DV256-90W	600-mil Plastic DIP
	IS27DV256-90PL	PLCC – Plastic Leaded Chip Carrier
	IS27DV256-90T	TSOP
120	IS27DV256-12W	600-mil Plastic DIP
	IS27DV256-12PL	PLCC – Plastic Leaded Chip Carrier
	IS27DV256-12T	TSOP
150	IS27DV256-15W	600-mil Plastic DIP
	IS27DV256-15PL	PLCC – Plastic Leaded Chip Carrier
	IS27DV256-15T	TSOP

ORDERING INFORMATION**Industrial Range: –40°C to +85°C**

Speed (ns)	Order Part Number	Package
90	IS27DV256-90PLI	PLCC – Plastic Leaded Chip Carrier
90	IS27DV256-90TI	TSOP
120	IS27DV256-12PLI	PLCC – Plastic Leaded Chip Carrier
120	IS27DV256-12TI	TSOP
150	IS27DV256-15PLI	PLCC – Plastic Leaded Chip Carrier
150	IS27DV256-15TI	TSOP